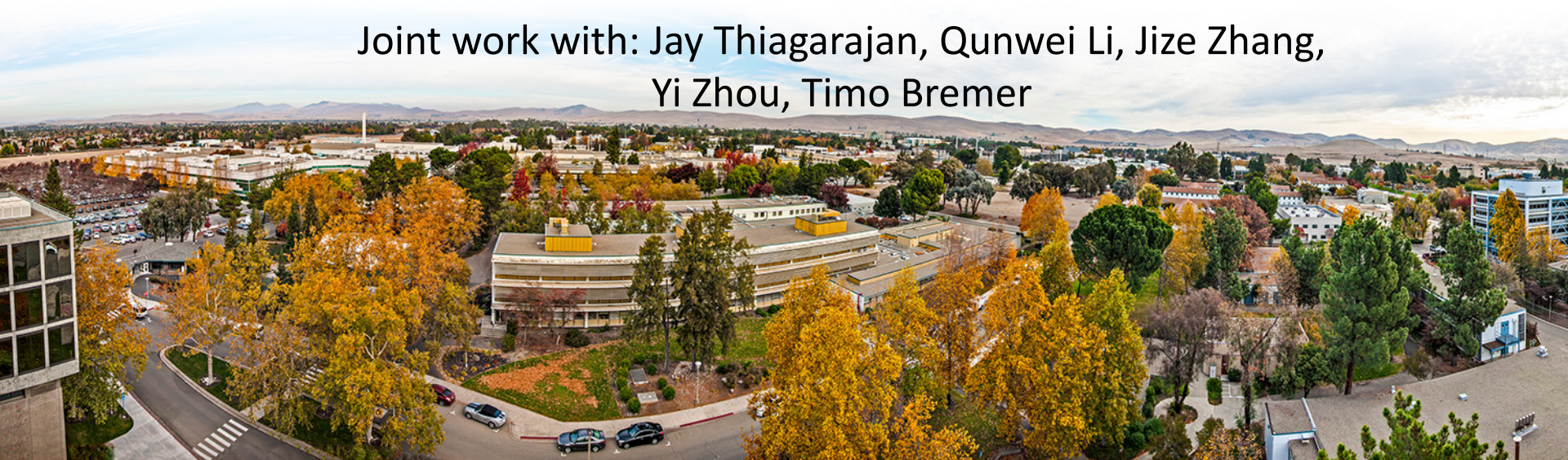


# Task-Agnostic Sample Design for Machine Learning

Bhavya Kailkhura

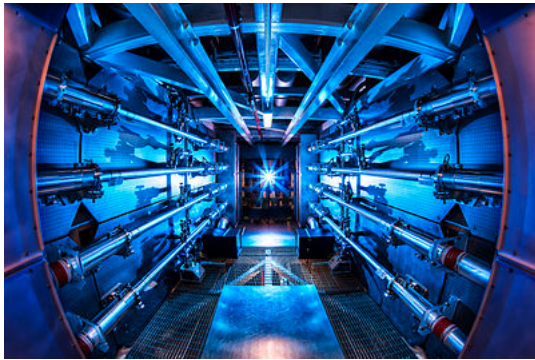
CASC, Lawrence Livermore National Lab

Joint work with: Jay Thiagarajan, Qunwei Li, Jize Zhang,  
Yi Zhou, Timo Bremer

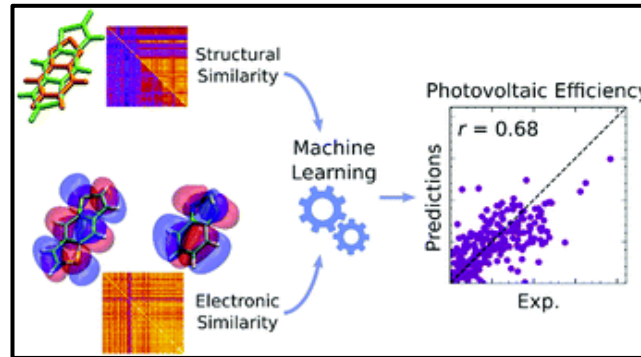


# ML provides incredible opportunities in science

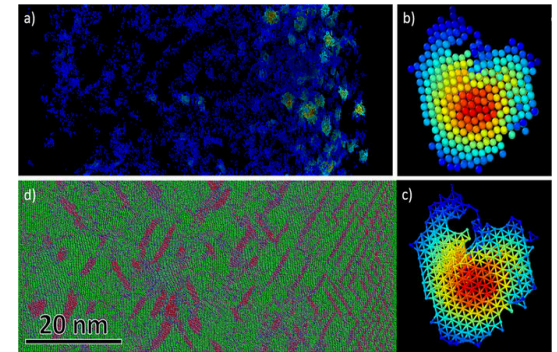
## Inertial Confinement Fusion



## Material Discovery

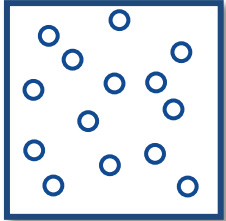


## Stockpile Stewardship



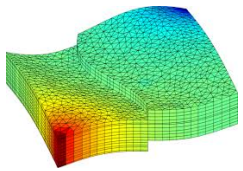
Scientific discoveries fundamentally rely on our understanding of high-fidelity experimental data

# A typical scientific data science pipeline



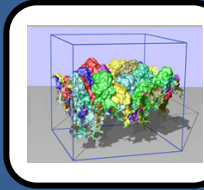
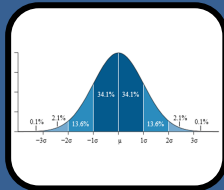
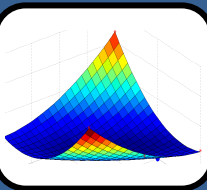
**SAMPLE  
DESIGN**

Decide random set of samples to cover the **N**-dimensional parameter space



**Experiments**

Run corresponding experiments to create a baseline of knowledge

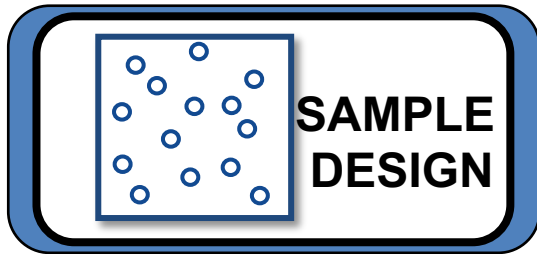


Analyze the resulting ensemble

- Build a reliable predictive model
- Optimization

Scientific experiments are **really expensive!**

# Sample design is crucial for the success of scientific ML



- Excellent generalization
- Low sampling rates
- Controlled variance

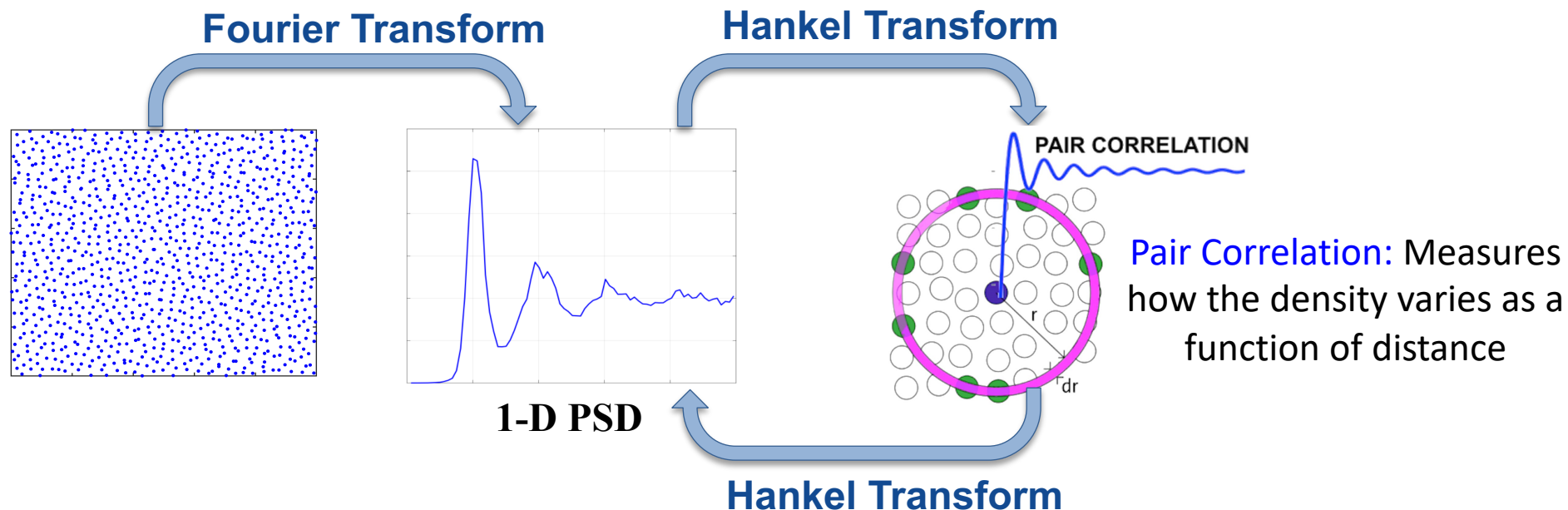
## Plethora of methods

- Uniform random
- Latin Hypercubes
- Voronoi Tessellation
- Orthogonal arrays
- Quasi Monte Carlo
- ...

Given a fixed sampling budget, which experiments to run to acquire the most amount of information?

# A new spectral sampling theory for sample design

Characterize spatial properties using the Pair Correlation Function (PCF) and develop a mathematical connection to Power Spectral Density (PSD)



A neat theoretical connection:

$$P(k) = 1 + \rho(2\pi)^{\frac{d}{2}} k^{1-\frac{d}{2}} H_{\frac{d}{2}-1} \left( r^{\frac{d}{2}-1} (G(r) - 1) \right)$$

# Risk minimization using Monte Carlo estimates

Consider the following general setup to learn the function  $h : X \rightarrow Y$  by minimizing the **population risk**:

$$R_P(h) \triangleq \mathbb{E}_{P(x,y)}[l(h(x), y)] = \int l(h(x), y) dP(x, y)$$

In general, the joint distribution  $P(x, y)$  is unknown, we minimize the **empirical risk**

$$R_S(h) \triangleq \frac{1}{N} \sum_{i=1}^N l(h(x_i), y_i)$$

The generalization error is defined as

$$\text{gen}(h) \triangleq \mathbb{E}_S[(R_P(h) - R_S(h))^2] = \text{bias}^2 + \text{var}(R_S(h))$$

# Connecting generalization error with spectral sampling

We restrict our analysis to homogeneous sampling patterns, which are unbiased

**Lemma 1.** *The generalization error in terms of the power spectra of both the sampling pattern and the loss function in the toroidal domain can be obtained as:*

$$gen(h) \triangleq \frac{1}{N} \int_{\Theta} \mathbb{E}(\mathcal{P}_S(\omega)) \mathcal{P}_l(\omega) d\omega \quad (8)$$

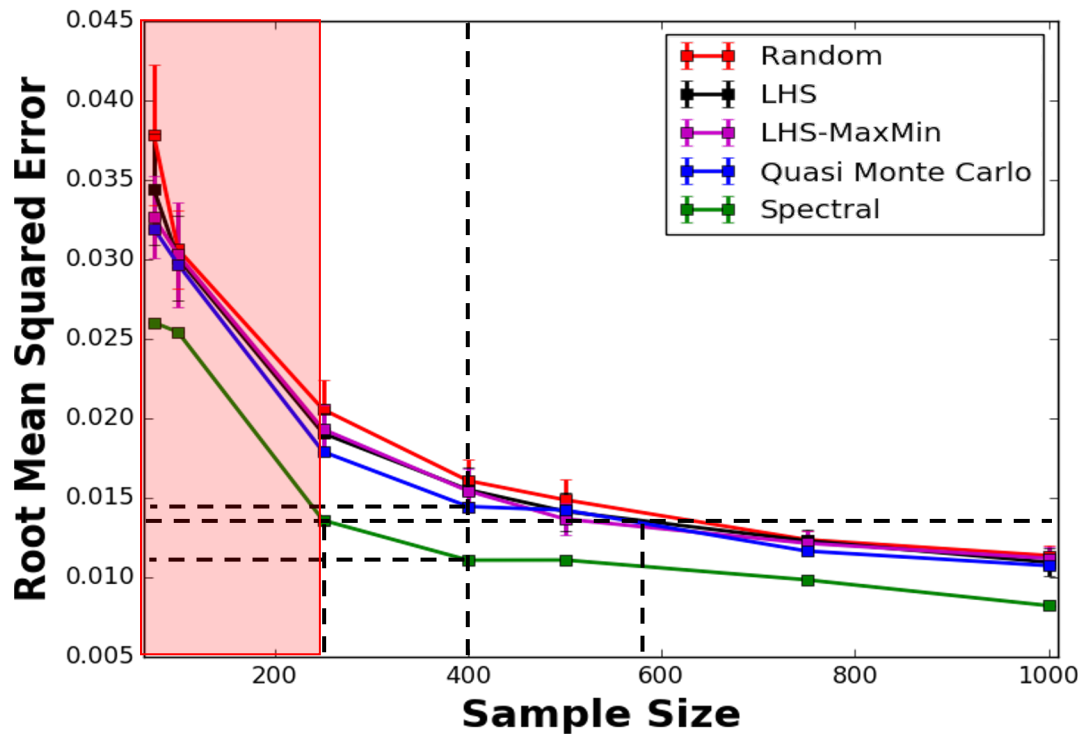
**Theorem 2.** *The generalization error for isotropic homogeneous sampling patterns (in polar coordinates) is given by*

$$gen(h) \triangleq \frac{\mu(\mathcal{S}^{d-1})}{N} \int_0^\infty \rho^{d-1} \mathbb{E}(\hat{\mathcal{P}}_S(\rho)) \hat{\mathcal{P}}_l(\rho) d\rho, \quad (9)$$

An ideal sampling power spectrum must attain zero values in the low frequency regime

# Predicting peak pressure in NIF 1-d hotspot simulator

We use random forest regressor to learn peak pressure by varying 2 input parameters and performance is evaluated on 10K unseen test samples



## Spectral sampling

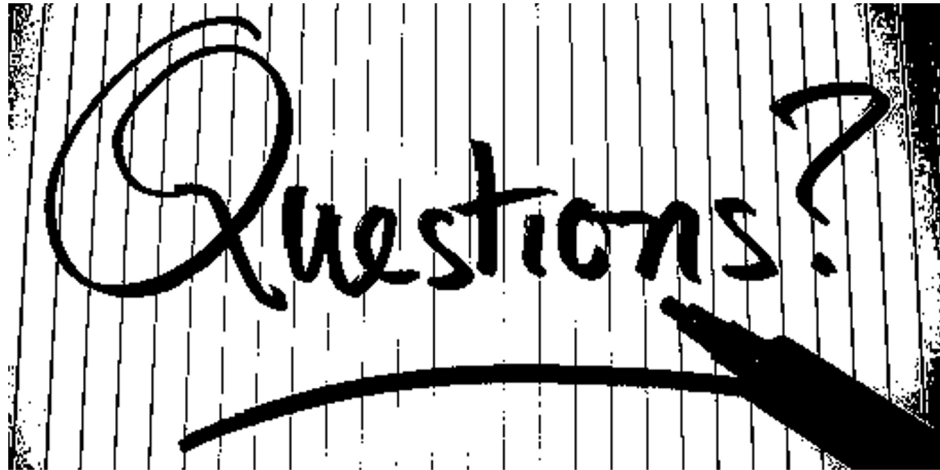
- ~ 30% less test error
- ~ 50% less samples
- Low Variance



# Summary

- A general theoretical framework for studying the generalization performance of task-agnostic sampling patterns
- Spectral sampling is an effective alternative to creating baseline of knowledge in small data scientific ML applications
- Exploiting the connection between Fourier and Spatial statistics enables the design of sampling patterns that outperform existing methods at low sampling rates

**Improved sample designs can enable unprecedented capabilities in computational sciences**



## Contact

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